# Lecture: Algorithmic Bioinformatics

Doctoral School, Université Dauphine, 2022



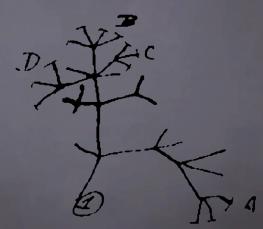




Université
Gustave Eiffel



I think





#### Motivation

- study relation Between species
- evolution of characteristics
- co-evolution (host-parasite)
- geological migration
- genetic development of viruses/diseases



#### Motivation

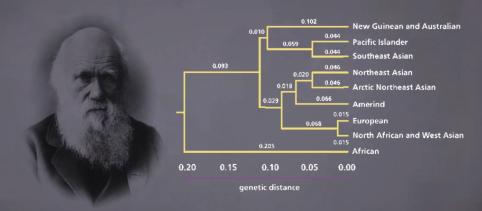
- study relation Between species
- evolution of characteristics
- co-evolution (host-parasite)
- geological migration
- genetic development of viruses/diseases

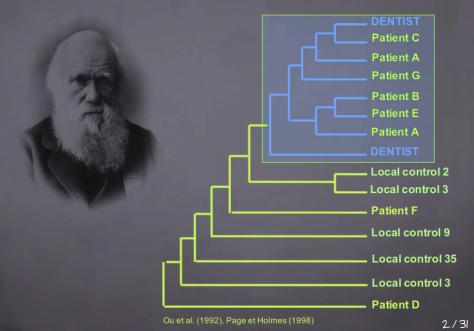
#### Evolution

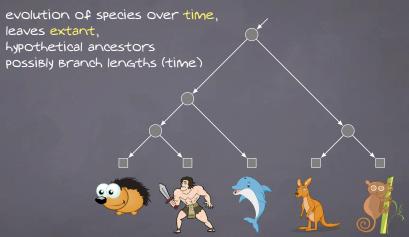
Genetic material changes over time

→ new species "Branch off"

"tree of life"

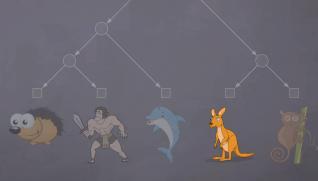






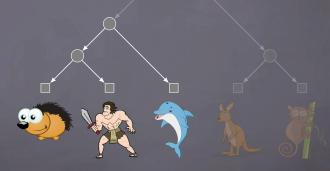
#### Notation

evolution of species over time, leaves extant, hypothetical ancestors possibly branch lengths (time)

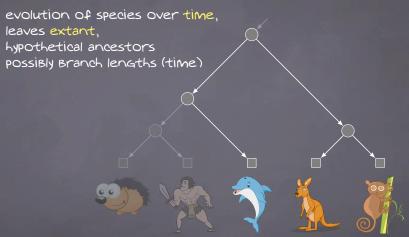


#### Notation

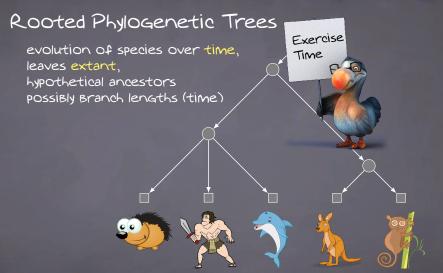
evolution of species over time, leaves extant, hypothetical ancestors possibly branch lengths (time)



#### Notation



#### Notation



#### Notation

taxon, cluster, triplet

"Polytomies"

history not clear  $\leadsto$  "soft" known "fan out"  $\leadsto$  "hard"

#### Exercise:

use xy|z  $\leftrightarrow$  LCA(xy)<LCA(xz)=LCA(xyz) to prove ab|c + Bc|d  $\rightarrow$  ac|d

similarity between genomes, leaves extant, internal vertices have no meaning possibly branch lengths (amount of change)

#### Notation

similarity between genomes, leaves extant, internal vertices have no meaning possibly branch lengths (amount of change)

#### Notation

similarity between genomes, leaves extant, internal vertices have no meaning possibly branch lengths (amount of change)

#### Notation

similarity between genomes, leaves extant, internal vertices have no meaning possibly branch lengths (amount of change)

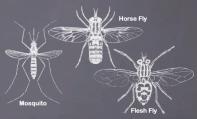
#### Notation

similarity between genomes, leaves extant, internal vertices have no meaning possibly branch lengths (amount of change)

#### Notation

#### Group Species By...

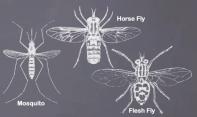
- morphology
- Behavior
- geography



Diptera = two wings

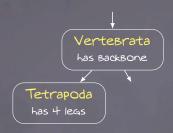
#### Group Species By.

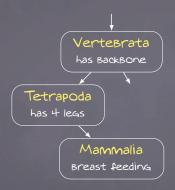
- morphology
- Behavior
- geography
- distance of sequences
- "genetic distance"
- etc.

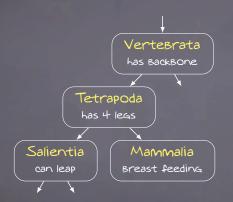


Diptera = two wings

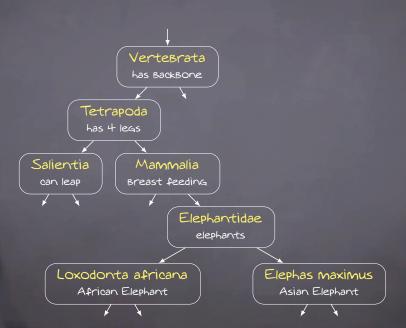


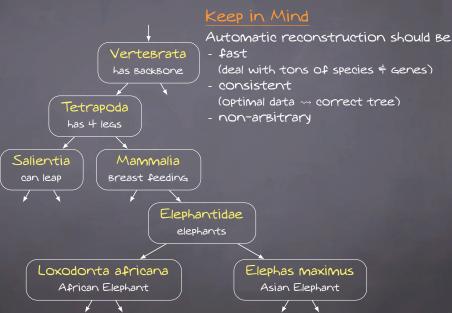












Idea: cluster hierarchically



Idea: cluster hierarchically



Idea: cluster hierarchically



Idea: merge closest clusters

Idea: cluster hierarchically



Idea: merge closest clusters









Idea: cluster hierarchically



ldea: merge closest clusters









Idea: cluster hierarchically



Idea: merge closest clusters

Branch lengths ??

assume molecular clock ~ ultrametric









Idea: cluster hierarchically



ldea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock 
~~ ultrametric









Idea: cluster hierarchically



Idea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock 

ultrametric









Idea: cluster hierarchically



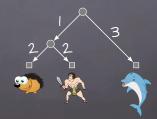
Idea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock ~ ultrametric





Idea: cluster hierarchically



Idea: merge closest clusters

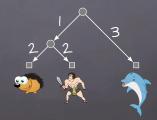
update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock 

w ultrametric







Idea: cluster hierarchically



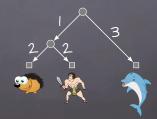
Idea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock ~ ultrametric





Idea: cluster hierarchically



28/3



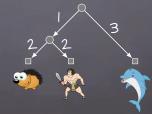
Idea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock ~ ultrametric





Idea: cluster hierarchically



28/3



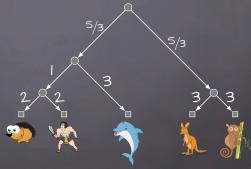
ldea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock w ultrametric



Idea: cluster hierarchically

### Unweighted Pair Group Method w/ Avg.

- find "closest pair"
- "join" them
- update distances & recurse



28/3



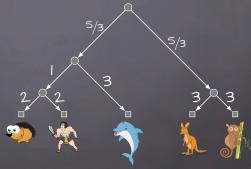
Idea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock w ultrametric



Idea: cluster hierarchically



Idea: merge closest clusters

### update matrix

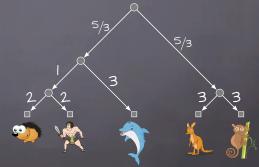
$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

### Branch lengths ??

assume molecular clock ~ ultrametric

### Unweighted Pair Group Method w/ Avg.

- find "closest pair"
- "join" them
- update distances & recurse



Idea: cluster hierarchically



### Unweighted Pair Group Method w/ Avg.

- find "closest pair"
- "join" them
- update distances & recurse

Idea: merge closest clusters

update matrix

 $\overline{d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}}$ 

Branch lengths ??

assume molecular clock w ultrametric



Idea: cluster hierarchically



### Unweighted Pair Group Method w/ Avg.

- find "closest pair"
- "join" them
- update distances ≠ recurse

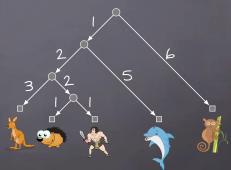
Idea: merge closest clusters

update matrix

$$d_{X \cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock ~ ultrametric



Idea: cluster hierarchically



### Unweighted Pair Group Method w/ Avg.

- find "closest pair"
- "join" them
- update distances ≠ recurse
- only accurate if ultrametric

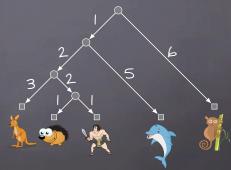
Idea: merge closest clusters

update matrix

$$d_{X\cup Y,Z} = \frac{|X|d_{X,Z} + |Y|d_{Y,Z}}{|X| + |Y|}$$

Branch lengths ??

assume molecular clock ~ ultrametric



What about unrooted trees? No root who molecular clock...

```
C || 8
D 9 |2 |0
A B C
```

What about unrooted trees? No root -- no molecular clock...

Problem: correct pairs may not be closest

B 9

C | 8

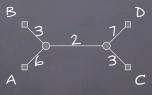
D 9 12 10

ABC

What about unrooted trees? No root  $\leadsto$  no molecular clock...

Problem: correct pairs may not be closest

C | 8 D 9 12 9 12 10



Problem: correct pairs may not be closest

### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_{Z} (d_{X,Z} + d_{Y,Z} d_{X,Y}) + 2d_{X,Y}$
- find max in Q
- join them
- update distances & recurse

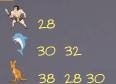
Problem: correct pairs may not be closest



### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_Z (d_{X,Z} + d_{Y,Z} d_{X,Y}) + 2d_{X,Y}$  find max in Q
- join them
- update distances & recurse

Problem: correct pairs may not be closest



28 36 32 28



### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_{Z} (d_{X,Z} + d_{Y,Z} d_{X,Y}) + 2d_{X,Y}$
- find max in Q
- join them
- update distances & recurse

### Theorem

 $Q_{X,Y}$  max  $\Leftrightarrow$  any tree T yielding Q has "cherry" (X,Y)



Problem: correct pairs may not be closest



### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_Z \left( d_{X,Z} + d_{Y,Z} d_{X,Y} \right) + 2d_{X,Y}$  find max in Q
- join them
- update distances & recurse

### update distances

$$d_{X \cup Y,Z} = 1/2 (d_{X,Z} + d_{Y,Z} - d_{X,Y})$$

$$\frac{2b(X) = \frac{\sum_{Z}(d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}}{2b(X) = \frac{\sum_{Z}(d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}}$$



Problem: correct pairs may not be closest



### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_{Z} (d_{X,Z} + d_{Y,Z} d_{X,Y}) + 2d_{X,Y}$
- find max in Q - join them
- update distances & recurse

### update distances

$$d_{X \cup Y,Z} = 1/2 (d_{X,Z} + d_{Y,Z} - d_{X,Y})$$

$$2b(X) = \frac{\sum_{Z}(d_{X,Z}-d_{Y,Z}+d_{X,Y})}{n-2}$$



Problem: correct pairs may not be closest





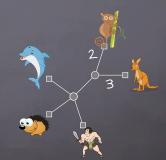
### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_Z \left( d_{X,Z} + d_{Y,Z} d_{X,Y} \right) + 2d_{X,Y}$  find max in Q
- join them
- update distances ≠ recurse

### update distances

$$d_{X \cup Y,Z} = 1/2 (d_{X,Z} + d_{Y,Z} - d_{X,Y})$$

$$\frac{1}{2b(X) = \frac{\sum_{Z}(d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}}$$



Problem: correct pairs may not be closest





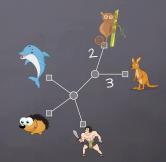
### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_Z \left( d_{X,Z} + d_{Y,Z} d_{X,Y} \right) + 2d_{X,Y}$  find max in Q
- join them
- update distances & recurse

### update distances

$$d_{X \cup Y,Z} = 1/2 (d_{X,Z} + d_{Y,Z} - d_{X,Y})$$

$$\frac{2b(X) = \frac{\sum_{Z}(d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}}{2b(X) = \frac{\sum_{Z}(d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}}$$



Problem: correct pairs may not be closest





### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_{Z} (d_{X,Z} + d_{Y,Z} d_{X,Y}) + 2d_{X,Y}$
- find max in Q
- join them
- update distances ≠ recurse

### update distances

$$d_{X \cup Y,Z} = 1/2 (d_{X,Z} + d_{Y,Z} - d_{X,Y})$$

$$\frac{1}{2b(X) = \frac{\sum_{Z}(d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}}$$



Problem: correct pairs may not be closest



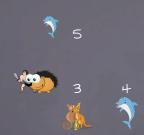
# Neighbor Joining (unrooted) - Build eccentricity matrix:

- Build eccentricity matrix:  $Q_{X,Y} = \sum_Z (d_{X,Z} + d_{Y,Z} d_{X,Y}) + 2d_{X,Y}$  find max in Q
- join them
- update distances & recurse

# update distances $d_{X \cup Y,Z} = \frac{1}{2} (d_{X,Z} + d_{Y,Z} - d_{X,Y})$ Branch lengths $2b(X) = \frac{\sum_{Z} (d_{X,Z} - d_{Y,Z} + d_{X,Y})}{n-2}$



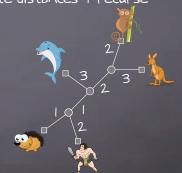
Problem: correct pairs may not be closest



### Neighbor Joining (unrooted)

- Build eccentricity matrix:  $Q_{X,Y} = \sum_{Z} \left( d_{X,Z} + d_{Y,Z} d_{X,Y} \right) + 2d_{X,Y}$
- find max in Q
- join them
- update distances ≠ recurse

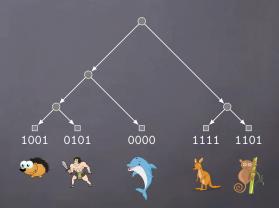
update distances 
$$d_{X \cup Y,Z} = \frac{1}{2} \left( d_{X,Z} + d_{Y,Z} - d_{X,Y} \right)$$
 Branch lengths 
$$2b(X) = \frac{\sum_{Z} (d_{X,Z} - d_{Y,Z} + d_{X,Y})}{2}$$



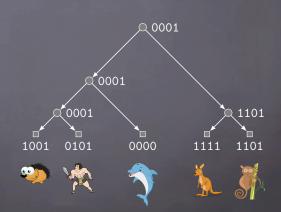




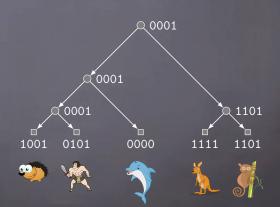




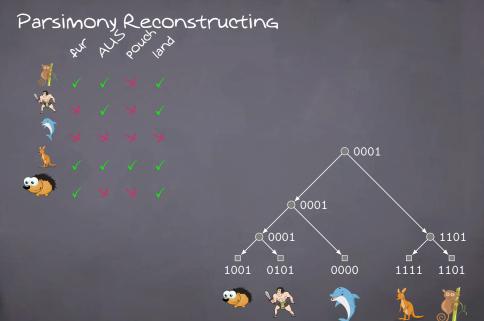








sum "distance" of endpoints of each edge

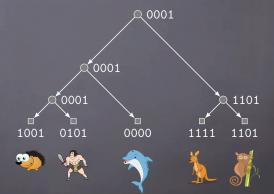


sum "distance" of endpoints of each edge ~> cost 6 (Hamming)



Small Parsimony Input: character state matrix M, rooted tree T

> Task: assign characters to internal nodes minimizing total cost

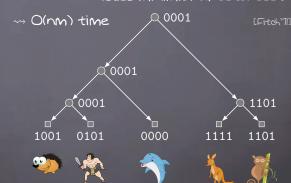




### Small Parsimony

Input: character state matrix M, rooted tree T

Task: assign characters to internal nodes minimizing total cost

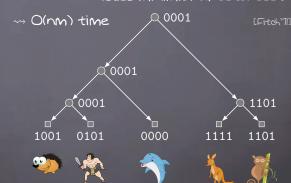




### Small Parsimony

Input: character state matrix M, rooted tree T

Task: assign characters to internal nodes minimizing total cost





Small Parsimony

Input: character state matrix M, rooted tree T

Task: assign characters to internal nodes minimizing total cost

~ O(nm) time

[Fitch'71]

### Large Parsimon

Input: character state matrix M

Task: find tree T & assign characters to internal nodes minimizing total cost

Algo (simple DFS):
Backtrack from v:
if v is leaf: R(v) = |aBel(v)|else if  $R(u) \cap R(w) = \emptyset$ :  $R(v) = R(u) \cup R(w)$ else:  $R(v) = R(u) \cap R(w)$ 



Small Parsimony

Input: character state matrix M, rooted tree T

Task: assign characters to internal nodes minimizing total cost

~ O(nm) time

[Fitch'71]

### Large Parsimon

Input: character state matrix M

Task: find tree T & assign characters to internal nodes minimizing total cost

→ NP-hard

Algo (simple DFS): Backtrack from v: if v is leaf:

else if R(v)=label(v)  $R(v) = R(w) = \emptyset$ :  $R(v) = R(u) \cup R(w)$ else:

 $\rightarrow R(v) = R(u) \cap R(w)$ 



### Small Parsimony

Input: character state matrix M, rooted tree T

Task: assign characters to internal nodes minimizing total cost

→ O(nm) time

[Fitch'71]

### Large Parsimon

Input: character state matrix M

Task: find tree T & assign characters to internal nodes minimizing total cost

~ NP-hard

Note: alignment is crucial!

### Maximum Likelihood Reconstruction

Idea: find a tree (with Branch lengths) under which evolution is most likely to have produced the observed characters/genomes

### Maximum Likelihood Reconstruction

Idea: find a tree (with Branch lengths) under which evolution is most likely to have produced the observed characters/genomes ~ need model of evolution

### Maximum Likelihood Reconstruction

dea: find a tree (with Branch lengths) under which evolution is most likely to have produced the observed characters/genomes ~ need model of evolution

### Jukes & Cantor Model

- each base evolves individually
- each Base occurs with equal frequency in the Genome
- constant rate  $\mu$  of mutation
- each base is equally likely to be result of mutation

#### Jukes & Cantor Model

- each base evolves individually
- each base occurs with equal frequency in the genome
- constant rate  $\mu$  of mutation
- each base is equally likely to be result of mutation

#### Generalized Time Reversible Model

- each base evolves individually
- each base X has a frequency  $\pi_X$  to occur in the genome
- each Base-substitution has its own rate of occurance

#### Jukes & Cantor Model

- each base evolves individually
- each base occurs with equal frequency in the genome
- constant rate  $\mu$  of mutation
- each base is equally likely to be result of mutation

#### Generalized Time Reversible Model

- each base evolves individually
- each base X has a frequency  $\pi_X$  to occur in the genome
- each Base-substitution has its own rate of occurance

compute likelihood, given tree & parameters ~> O(mn) time

dea: find a tree (with Branch lengths) under which evolution is most likely to have produced the observed characters/genomes ~ need model of evolution

#### Jukes & Cantor Model

- each base evolves individually
- each base occurs with equal frequency in the genome
- constant rate  $\mu$  of mutation
- each base is equally likely to be result of mutation

#### Generalized Time Reversible Model

- each base evolves individually
- each base X has a frequency  $\pi_X$  to occur in the genome
- each Base-substitution has its own rate of occurance

compute likelihood, given tree \$ parameters \$\infty\$ O(mn) time find Best tree \$ parameters \$\infty\$ NP-hard

dea: find a tree (with Branch lengths) under which evolution is most likely to have produced the observed characters/genomes wheed model of evolution

#### Jukes & Cantor Model

- each base evolves individually
- each Base occurs with equal frequency in the Genome
- constant rate  $\mu$  of mutation
- each base is equally likely to be result of mutation

#### Generalized Time Reversible Model

- each base evolves individually
- each base X has a frequency  $\pi_X$  to occur in the genome
- each Base-substitution has its own rate of occurance

compute likelihood, given tree & parameters  $\leftrightarrow$  O(mn) time find Best tree & parameters  $\leftrightarrow$  NP-hard  $\rightsquigarrow$  local search in the tree space

Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

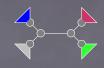
change any configuration of 4 (3) "neighboring" subtrees into another





Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





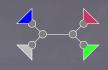
#### Subtree Prune & Regraft





Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





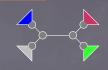
#### Subtree Prune & Regraft





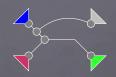
Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





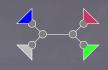
#### Subtree Prune & Regraft





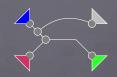
Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





#### Subtree Prune & Regraft





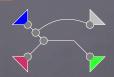
Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





#### Subtree Prune & Regraft





Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

change any configuration of 4 (3) "neighboring" subtrees into another





#### Subtree Prune & Regraft

Break any edge uv \$
connect v to any edge of
the component of u





## Tree Bisection & Reconnection



Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

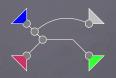
change any configuration of 4 (3) "neighboring" subtrees into another





#### Subtree Prune & Regraft

Break any edge uv \$
connect v to any edge of
the component of u





## Tree Bisection & Reconnection





Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

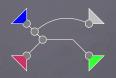
change any configuration of 4 (3) "neighboring" subtrees into another





#### Subtree Prune & Regraft

Break any edge uv \$
connect v to any edge of
the component of u





## Tree Bisection & Reconnection



Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

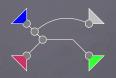
change any configuration of 4 (3) "neighboring" subtrees into another





#### Subtree Prune & Regraft

Break any edge uv \$
connect v to any edge of
the component of u





## Tree Bisection & Reconnection



Observe: a tree and a rearrangement operation span a space Nearest Neighbor Interchange

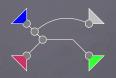
change any configuration of 4 (3) "neighboring" subtrees into another





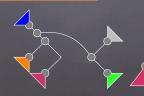
#### Subtree Prune & Regraft

Break any edge uv \$
connect v to any edge of
the component of u



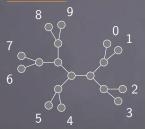


## Tree Bisection & Reconnection





#### Exercise: turn into (any) caterpillar:



Exercise: how are the distances related?



## Checking Robustness - Bootstrap Method

suppose:  $method \times yields$  tree T from  $n \times m$  character-state matrix M repeat k times the following experiment:

- 1. draw m columns from M (with repetition)
- 2. use X to compute Ti

Finally, for each Branch of T, check how often it occurs in the  $T_i \leadsto$  "Bootstrap value" measures robustness ("support") of each Branch

- 1. Get Genomes of multiple species
- 2. extract "genes" using START & STOP codons
- 3. cluster genes in "families" of similar genes
- 4. within each family, infer a "gene tree" using dissimilarities
- Build a consensus among the gene trees 
   "species tree"
   (Note: species tree may differ significantly from individual gene trees)
- 6. reconcile all gene trees with the species tree to learn the evolution of those genes

- 1. Get Genomes of multiple species
- 2. extract "genes" using START & STOP codons
- 3. cluster genes in "families" of similar genes
- 4. within each family, infer a "gene tree" using dissimilarities
- Build a consensus among the gene trees 
   "species tree"
   (Note: species tree may differ significantly from individual gene trees)
- 6. reconcile all gene trees with the species tree to learn the evolution of those genes

- 1. Get Genomes of multiple species
- 2. extract "genes" using START & STOP codons
- 3. cluster genes in "families" of similar genes
- 4. within each family, infer a "gene tree" using dissimilarities
- 5. Build a consensus among the gene trees  $\leadsto$  "species tree" (Note: species tree may differ significantly from individual gene trees)
- 6. reconcile all gene trees with the species tree to learn the evolution of those genes

- 1. Get Genomes of multiple species
- 2. extract "genes" using START & STOP codons
- 3. cluster genes in "families" of similar genes
- 4. within each family, infer a "sene tree" using dissimilarities
- 5. Build a consensus among the gene trees  $\leadsto$  "species tree" (Note: species tree may differ significantly from individual gene trees)
- 6. reconcile all gene trees with the species tree to learn the evolution of those genes

Idea: find root partition  $\neq$  recurse (as long as there are  $\geq 3$  taxa)



# Algo | Each et a|81| | Build Graph G with edge | UV ⇔ ∃UV | X | 2 recurse for each component of G | 3. plug subtrees to root

Idea: find root partition  $\neq$  recurse (as long as there are  $\geq$ 3 taxa)





b	С
d	а
	f

#### Algo

[Aho et al'81]

- 1. Build Graph G with edge uv ⇔∃uv|x
- 2. recurse for each component of G
- 3. Plug subtrees to root

Idea: find root partition & recurse (as long as there are >3 taxa)





#### Algo

[Aho et al'81]

- 1. Build Graph G with edge uv ⇔∃uv|x
- 2. recurse for each component of G
- 3. Plug subtrees to root

Idea: find root partition & recurse (as long as there are >3 taxa)



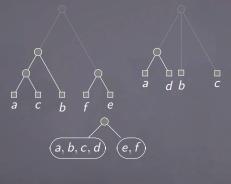


Algo

[Aho et al'8]

- 1. Build Graph G with edge uv ⇔∃uv|x
- 2. recurse for each component of G
- 3. Plug subtrees to root

Idea: find root partition & recurse (as long as there are >3 taxa)



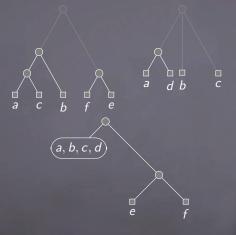


Algo

[Aho et al'8]

- 1. Build Graph G with edge uv ⇔∃uv|x
- 2. recurse for each component of G
- 3. Plug subtrees to root

Idea: find root partition & recurse (as long as there are >3 taxa)



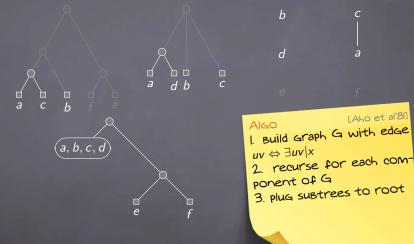


#### AIGO

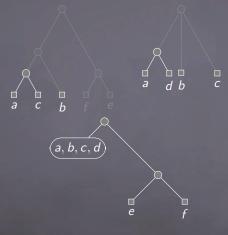
[Aho et al'81]

- 1. Build Graph G with edge uv ⇔∃uv|x
  - 2. recurse for each component of G
  - 3. Plug subtrees to root

Idea: find root partition  $\neq$  recurse (as long as there are  $\geq$ 3 taxa)



Idea: find root partition & recurse (as long as there are >3 taxa)



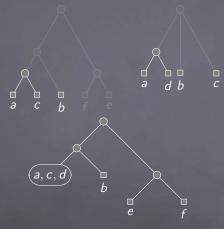


#### AIGO

[Aho et al'81]

- 1. Build Graph G with edge uv ⇔∃uv|x
  - 2. recurse for each component of G
  - 3. Plug subtrees to root

Idea: find root partition  $\neq$  recurse (as long as there are  $\geq$ 3 taxa)



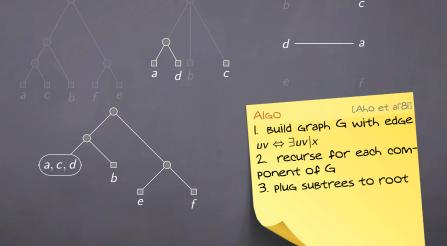


#### AIGO

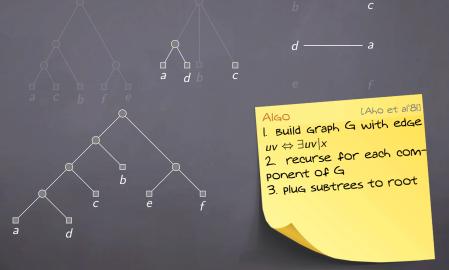
[Aho et al'81]

- 1. Build Graph G with edge uv ⇔∃uv|x
- 2. recurse for each component of G
- 3. Plug subtrees to root

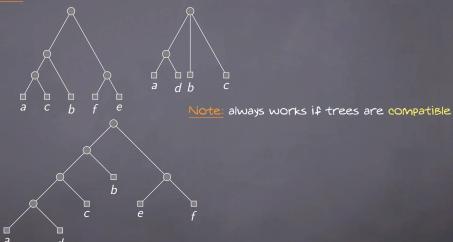
Idea: find root partition  $\neq$  recurse (as long as there are  $\geq 3$  taxa)



Idea: find root partition  $\neq$  recurse (as long as there are  $\geq$ 3 taxa)

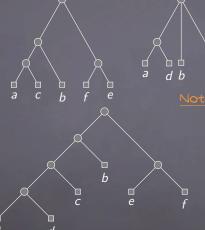


 $\frac{1}{2}$  dea: find root partition  $\frac{1}{2}$  recurse (as long as there are  $\geq 3$  taxa)



## Supertrees - "Build" Algorithm

Idea: find root partition  $\neq$  recurse (as long as there are  $\geq$ 3 taxa)



b c
Note: always works if trees are compatible

#### incompatible

- largest compatible subset
   NP-hard (even for triplets)
- voting schemes
   (each tree votes for their clades)
- reinterpret clades as characters,
   combine into matrix \( \frac{1}{2} \) reconstruct

### Consensi of Non-Agreeing Trees







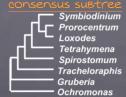
Ochromonas

Symbiodinium

Prorocentrum

#### strict consensus









## Reconstruction by Gene Trees

### A Common Method For Reconstructing Trees

- 1. Get Genomes of multiple species
- 2. extract "genes" using START & STOP codons
- 3. cluster genes in "families" of similar genes
- 4. within each family, infer a "sene tree" using dissimilarities
- 5. Build a consensus among the gene trees  $\leadsto$  "species tree" (Note: species tree may differ significantly from individual gene trees)
- 6. reconcile all gene trees with the species tree to learn the evolution of those genes

## Reconstruction by Gene Trees

### A Common Method For Reconstructing Trees

- 1. Get Genomes of multiple species
- 2. extract "genes" using START & STOP codons
- 3. cluster genes in "families" of similar genes
- 4. within each family, infer a "gene tree" using dissimilarities
- Build a consensus among the gene trees --- "species tree"
   (Note species tree may differ significantly from individual gene trees)
- reconcile all gene trees with the species tree to learn the evolution of those genes

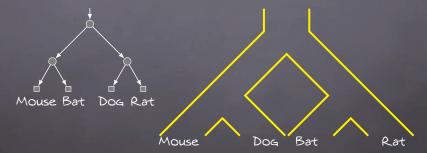
## The History of a Gene Family

#### Recall

gene = "functional element" of DNA, clustered into gene-families



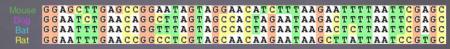
each family yields a tree depicting its history  $\leftrightarrow$  "gene tree" consensus of the gene trees yields "species tree" But: what did really happen???



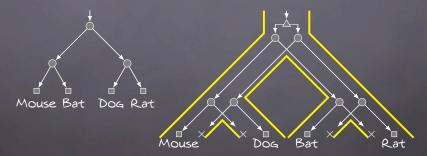
## The History of a Gene Family

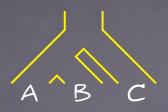
#### Recall

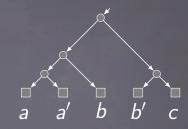
gene = "functional element" of DNA, clustered into gene-families



each family yields a tree depicting its history  $\leftrightarrow$  "gene tree" consensus of the gene trees yields "species tree" But: what did really happen???



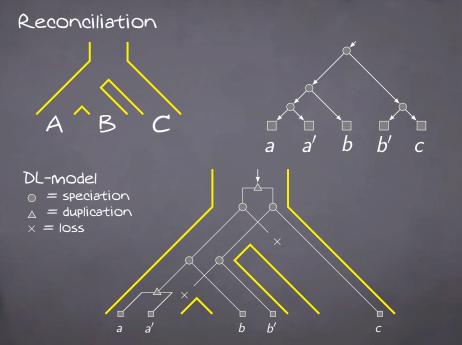




#### Embedding Rules

gene tree G, species tree 5

- Mapping ho:V(G) o V(S)
- $\ell$  is leaf in  $G \leadsto 
  ho(\ell)$  "corresponds" to  $\ell$  (a o A, a' o A, etc.)
- $u \in V(G)$  is called <u>duplication</u> if  $\rho(u) = \rho(c)$  for any child c of u in G
- all non-leaves of G that not duplications are called <u>speciations</u>
- each edge uv of G incurs a loss-cost equal to the number of edges in the  $\rho(u)$ - $\rho(v)$ -path in S minus I if v is a speciation or O if v is a duplication



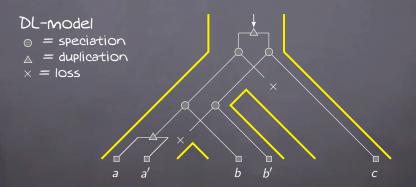
Goal: embed gene tree into species tree (extant genes must map to their species)

#### Max Likelihood

find most probable embedding (computationally expensive)

### Parsimony

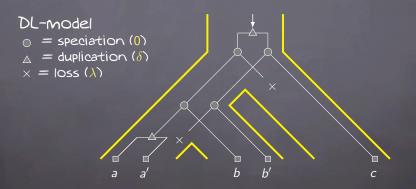
find embedding minimizing #events (possibly weighted)



Parsimonious Reconciliation Input: species tree S, Gene tree G,  $\delta,\lambda\in\mathbb{N}$ 

Task: embed G in S, minimizing the weighted sum of events

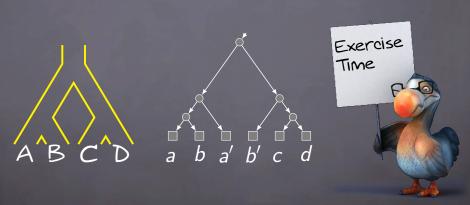
Result: LCA-assignment solves this optimally in O(|S|+|G|)



Parsimonious Reconciliation Input: species tree S, S, A, T  $\in \mathbb{N}$ 

Task: embed G in S, minimizing the weighted sum of events

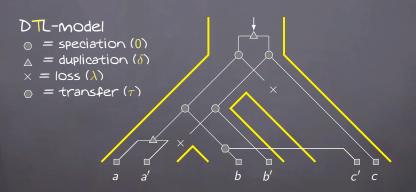
Result: LCA-assignment solves this optimally in O(|S|+|G|)



Parsimonious Reconciliation input: species tree S, gene tree G,  $\delta$ ,  $\lambda$ ,  $\tau \in \mathbb{N}$ 

Task: embed G in S, minimizing the weighted sum of events

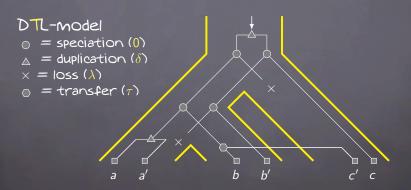
Result: LCA-assignment solves this optimally in O(|S|+|G|)



Parsimonious Reconciliation input: species tree S, gene tree G,  $\delta$ ,  $\lambda$ ,  $\tau \in \mathbb{N}$ 

Task: embed G in S, minimizing the weighted sum of events

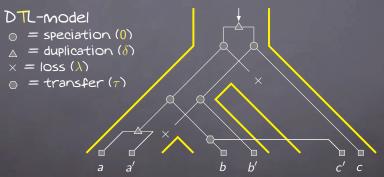
Result: LCA-assignment solves this optimally in O(|S|+|G|)
Tevents only between co-existing species witime constraints which NP-hard



Parsimonious Reconciliation hput: species tree G,  $\delta$ ,  $\lambda$ ,  $\tau \in \mathbb{N}$ 

Task: embed G in S, minimizing the weighted sum of events

Result: LCA-assignment solves this optimally in O(|S|+|G|) Tevents only Between co-existing species  $\leadsto$  time constraints  $\leadsto$  NP-hard ldea: take dated species tree  $\leadsto$  O(|S|<sup>2</sup>|G|) time



## Comparing Phylogenetic Trees

#### Distance Measures

- Nearest Neighbor Interchange
- Subtree Prune & Regraft
- Tree Bisection & Reconnection

# Comparing Phylogenetic Trees

#### Distance Measures

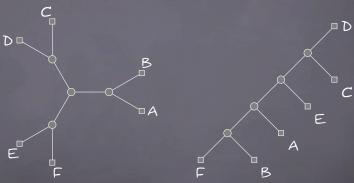
- Nearest Neighbor Interchange
- Subtree Prune & Regraft
- Tree Bisection & Reconnection
- now: via agreement-forests

## Comparing Phylogenetic Trees

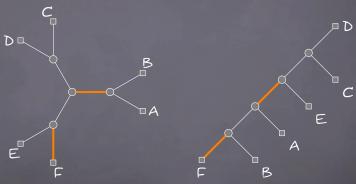
#### Distance Measures

- Nearest Neighbor Interchange
- Subtree Prune & Regraft
- Tree Bisection & Reconnection
- now: via agreement-forests
- Robinson-Foulds distance
- quartet/triplet distance

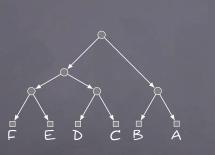
#### Definition

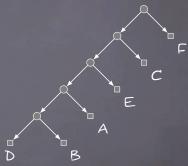


#### Definition

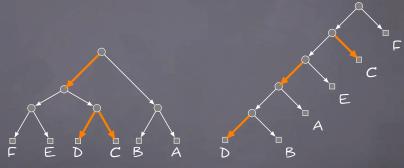


#### Definition





#### Definition



#### Definition

A forest F is called agreement forest of trees  $T_1$  and  $T_2$  if F can be obtained from  $T_1$  and  $T_2$  by removing edges.

#### Theorem [Allen & Steel, 'Ol]

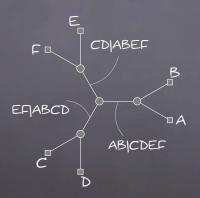
TBR-distance( $T_1, T_2$ ) = #trees in smallest agreement forest - | NP-hard to compute

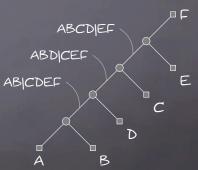
#### Theorem [Bordewich & Semple, '04]

rSPR-distance( $T_1, T_2$ ) = #trees in smallest rooted agreement forest - | NP-hard to compute

#### Definition

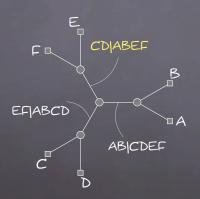
 $RF(T_1,T_2) = \#splits/clusters$  occurring in exactly one of  $T_1$  and  $T_2$  = edge-contraction distance a common tree Note: observe relation to NNI:  $RF(T_1,T_2) < 2$  NNI( $T_1,T_2$ )





#### Definition

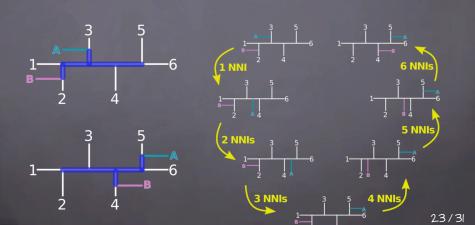
 $RF(T_1,T_2) = \#splits/clusters$  occurring in exactly one of  $T_1$  and  $T_2$  = edge-contraction distance a common tree Note: observe relation to NNI:  $RF(T_1,T_2) < 2$  NNI( $T_1,T_2$ )





#### Definition

 $RF(T_1,T_2) = \#splits/clusters$  occurring in exactly one of  $T_1$  and  $T_2$  = edge-contraction distance a common tree Note: observe relation to NNI:  $RF(T_1,T_2) < 2$  NNI( $T_1,T_2$ )



#### Definition

 $RF(T_1,T_2)=\#splits/clusters$  occurring in exactly one of  $T_1$  and  $T_2$  = edge-contraction distance a common tree

Note: observe relation to NNI:  $RF(T_1,T_2) \le 2$  NNI $(T_1,T_2)$ Note: splits correspond to clusters when rooted at last leaf

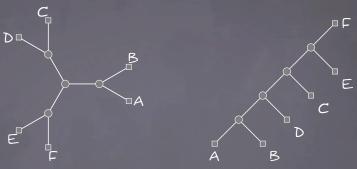
### Day's Algorithm (common clusters in O(n))

[Day'85]

- 1. relatel all leaves such that leaves continuous in  $T_1$
- 2. each node in  $T_1$  knows:

L = smallest leaf in cluster  $\stackrel{\protect}{\leftarrow} R$  = largest leaf in cluster  $\stackrel{\hfill}{\sim}$  note  $T_1$ 's clusters in hash-set

- 3. each node in  $T_2$  knows: L, R, and size N of its cluster
- 4. each node in  $T_2$  checks [L,R] in table only if R-L=N-1 (lookup in  $T_1$ 's cluster-set in O(1) (average) time)



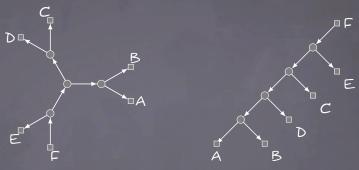
### Day's Algorithm (common clusters in O(n))

[Day'85]

- 1. related all leaves such that leaves continuous in  $T_1$
- 2. each node in  $T_1$  knows:

L = smallest leaf in cluster  $\Leftrightarrow R =$  largest leaf in cluster  $\Leftrightarrow$  note  $T_1$ 's clusters in hash-set

- 3. each node in  $T_2$  knows: L, R, and size N of its cluster
- 4. each node in  $T_2$  checks [L,R] in table only if R-L=N-1 (lookup in  $T_1$ 's cluster-set in O(1) (average) time)



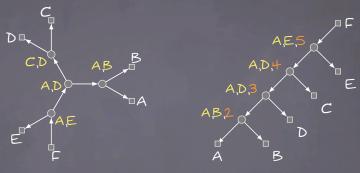
### Day's Algorithm (common clusters in O(n))

[Day'85]

- 1. relabel all leaves such that leaves continuous in  $T_1$
- 2. each node in  $T_1$  knows:

 $L = \text{smallest leaf in cluster} \Leftrightarrow$  $\sim \text{note } T_1$ 's clusters in hash-set R =largest leaf in cluster

- 3. each node in  $T_2$  knows: L, R, and size N of its cluster
- 4. each node in  $T_2$  checks [L,R] in table only if R-L=N-1 (lookup in  $T_1$ 's cluster-set in O(1) (average) time)



### Day's Algorithm (common clusters in O(n))

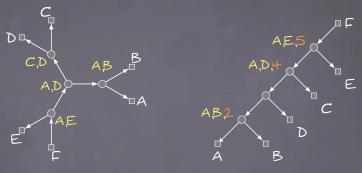
[Day'85]

- 1. relabel all leaves such that leaves continuous in  $T_1$
- 2. each node in  $T_1$  knows:

L = smallest leaf in cluster  $\Rightarrow$  note  $T_1$ 's clusters in hash-set

R =largest leaf in cluster

- 3. each node in  $T_2$  knows: L, R, and size N of its cluster
- 4. each node in  $T_2$  checks [L,R] in table only if R-L=N-1 (lookup in  $T_1$ 's cluster-set in O(1) (average) time)



### Day's Algorithm (common clusters in O(n))

[Day'85]

- 1. relabel all leaves such that leaves continuous in  $T_1$
- 2. each node in  $T_1$  knows:

L = smallest leaf in cluster  $\Leftrightarrow R =$  largest leaf in cluster  $\Leftrightarrow$  note  $T_1$ 's clusters in hash-set

- 3. each node in  $T_2$  knows: L, R, and size N of its cluster
- 4. each node in  $T_2$  checks [L,R] in table only if R-L=N-1 (lookup in  $T_1$ 's cluster-set in O(1) (average) time)

## Quartet/Triplet Distance

### Definition

 $Q/T(T_1,T_2)=\#$  quartets/triplets occur. in exactly one of  $T_1$  and  $T_2$ 

## Quartet/Triplet Distance

#### Definition

 $Q/T(T_1,T_2)=\#$ quartets/triplets occur. in exactly one of  $T_1$  and  $T_2$ 

### computing Q-distance (Binary trees) (Bryant et al. 100)

- 1. each edge uv has 4 sets (2 clusters for each of  $u \neq v$ )
- 2. Quartet AB|CD "Belongs" to edge e if e splits AB|CD and e touches AB-path  $\leadsto$  each Quartet is owned exactly once
- 3.  $\forall uv \in T_1 \neq qr \in T_2$ : intersect + sets of uv with split of qr in  $T_2$
- 4. sizes of intersections can be precomputed bottom-up in  $O(n^2)$  time

## Quartet/Triplet Distance

#### Definition

 $Q/T(T_1,T_2)=\#$  quartets/triplets occur. in exactly one of  $T_1$  and  $T_2$ 

### computing Q-distance (Binary trees) (Bryant et al. '00]

- 1. each edge uv has 4 sets (2 clusters for each of  $u \neq v$ )
- 2. Quartet AB|CD "Belongs" to edge e if e splits AB|CD and e touches AB-path  $\leadsto$  each Quartet is owned exactly once
- 3.  $\forall uv \in T_1 \neq qr \in T_2$ : intersect 4 sets of uv with split of qr in  $T_2$
- 4. sizes of intersections can be precomputed bottom-up in  $O(n^2)$  time

### State of the Art

count conflict quartets/triplets  $\leadsto O(n\log n)$  time enumerate conflict quartets  $\leadsto O(n^2+d)$  time enumerate conflict triplets  $\leadsto O(n+d)$  time

[Brodal et al.'13] [Bryant et al.'00] [Weller'17]

# Phylogenetic Networks

### Observation

Trees cannot capture hybridization



## Phylogenetic Networks

### Observation

Trees cannot capture hybridization ~> phylogenetic network



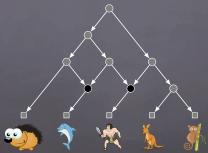
## Phylogenetic Networks

#### Observation

Trees cannot capture hybridization  $\leadsto$  phylogenetic network

#### Definition

evolutionary network N= rooted DAG, leaves labeled (taxa) reticulations R= vertices of in-degree  $\geq 2$  ginary = all inner vertices degree 3 glock = maximal biconnected component display T= subdivision of T is a subgraph



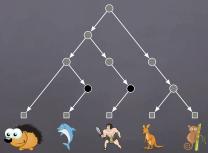
# Phylogenetic Networks

#### Observation

Trees cannot capture hybridization  $\leadsto$  phylogenetic network

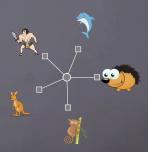
#### Definition

evolutionary network N= rooted DAG, leaves labeled (taxa) reticulations R= vertices of in-degree  $\geq 2$  ginary = all inner vertices degree 3 glock = maximal biconnected component display T= subdivision of T is a subgraph



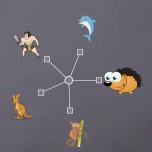
split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., 104]





split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., O4]





split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., O4]





split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., 104]





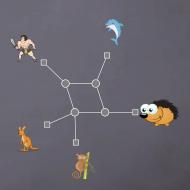
split = Bipartition of set of taxa
splits A|B = X|Y incompatible if Both A = B intersect Both X = Y
Convex Hull Algorithm [Holland et al., O4]





split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., '04]





split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., 104]

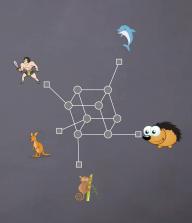




c.f.: Neighbor Net (Bryant & Moulton;03) (for circular splits)

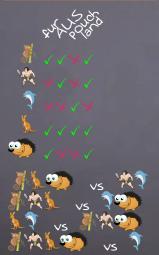
split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., O4]

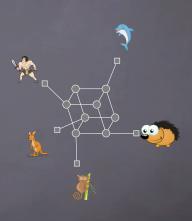




c.f.: Neighbor Net [Bryant & Moulton;03] (for circular splits)

split = Bipartition of set of taxa
splits A|B & X|Y incompatible if Both A & B intersect Both X & Y
Convex Hull Algorithm [Holland et al., 104]





c.f.: Neighbor Net (Bryant & Moulton;03) (for circular splits)

## Strategy

- 1. list all splits of all input trees
- 2. extend splits to full taxa using "Z-closure"
- 3. Build consensus

### Strategy

- 1. list all splits of all input trees
- 2. extend splits to full taxa using "Z-closure"
- 3. Build consensus

Experimental Study - 106 gene trees (yeast)

S. kudriavzevii
S. paradoxus
S. cerevisiae
S. mikatae
S. bayanus
S. castelli
C. albicans

#### Strategy

- 1. list all splits of all input trees
- 2. extend splits to full taxa using "Z-closure"
- 3. Build consensus

Experimental Study - 106 Gene trees (yeast)

S. kudriavzevii S. bayanus
S. paradoxus S. castelli
C. albicans
S. cerevisiae
S. mikatae
S. kluyveri

#### Strategy

- 1. list all splits of all input trees
- 2. extend splits to full taxa using "Z-closure"
- 3. Build consensus

Experimental Study - 106 gene trees (yeast)

[Rokas et al.'03, Holland et al.'04]

S. kudriavzevii S. bayanus

S. paradoxus

S. castelli

S. cerevisiae

S. kluyveri

C. albicans

S. mikatae

### Strategy

- 1. list all splits of all input trees
- 2. extend splits to full taxa using "Z-closure"
- 3. Build consensus

## Experimental Study - 106 gene trees (yeast)

S. kudriavzevii
S. paradoxus
S. castelli
S. cerevisiae
S. mikatae
S. kluyveri

#### Observation

rooted network: cluster of  $u \subseteq$  cluster of  $v \Leftrightarrow u \le v \Rightarrow$  rooted network is hasse diagram of its clusters

#### Observation

rooted network: cluster of u  $\subseteq$  cluster of v  $\Leftrightarrow$  u  $\le$  v  $\leadsto$  rooted network is hasse diagram of its clusters

#### Example

 $\{abcd\}, \{cdefGh\}, \{cdefG\}, \{efGh\}, \{cde\}, \{efG\}, \{ab\}, \{cd\}, \{fG\}\}\}$ 

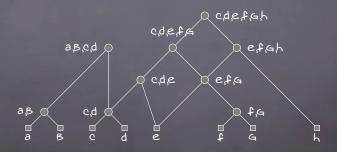


#### Observation

rooted network: cluster of  $u \subseteq cluster$  of  $v \Leftrightarrow u \le v \Rightarrow rooted$  network is hasse diagram of its clusters

#### Example

 $\{abcd\}, \{cdefGh\}, \{cdefG\}, \{efGh\}, \{cde\}, \{efG\}, \{ab\}, \{cd\}, \{fG\}\}\}$ 

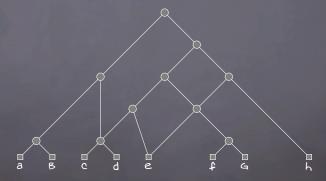


#### Observation

rooted network: cluster of  $u \subseteq$  cluster of  $v \Leftrightarrow u \le v \Leftrightarrow$  rooted network is hasse diagram of its clusters

#### Example

 $\{ab,cd\},\{cde,fgh\},\{cde,fg\},\{e,fgh\},\{cde\},\{e,fg\},\{ab\},\{cd\},\{fg\}\}$ 

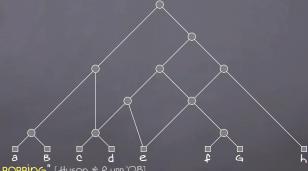


#### Observation

rooted network: cluster of  $u \subseteq$  cluster of  $v \Leftrightarrow u \le v \Leftrightarrow$  rooted network is hasse diagram of its clusters

#### Example

 $\{aB,cd\},\{cde,f,g,h\},\{cde,f,g\},\{e,f,g\},\{cde\},\{e,f,g\},\{cd\},\{f,g\}\}$ 



c.f. "cluster popping" [Huson & Rupp, '08]

#### Observation

rooted network: cluster of  $u \subseteq cluster$  of  $v \Leftrightarrow u \le v \Rightarrow rooted$  network is hasse diagram of its clusters

#### Problem

may produce more reticulations than necessary to explain the data

#### Observation

rooted network: cluster of  $u \subseteq cluster$  of  $v \Leftrightarrow u \le v \Rightarrow rooted$  network is hasse diagram of its clusters

#### Problem

may produce more reticulations than necessary to explain the data

Hybridization Number Input: set of trees T, int k

Question: Is there a network with  $\leq k$  reticulations displaying all trees in  $\mathcal{T}$ ?

#### Observation

rooted network: cluster of  $u \subseteq cluster$  of  $v \Leftrightarrow u \le v \Rightarrow rooted$  network is hasse diagram of its clusters

#### Problem

may produce more reticulations than necessary to explain the data

Hybridization Number Input: set of trees T, int k

Question: Is there a network with  $\leq k$  reticulations displaying all trees in  $\mathcal{T}$ ?

#### Observation

rooted network: cluster of  $u \subseteq cluster$  of  $v \Leftrightarrow u \le v \Rightarrow rooted$  network is hasse diagram of its clusters

#### Problem

may produce more reticulations than necessary to explain the data

Hybridization Number Input: set of trees T, int k

Question: Is there a network with  $\leq k$  reticulations displaying all trees in T?

→ NP-hard for 2 trees (Bordewich & Semple, 107)

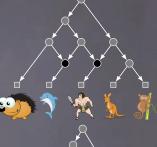
Note:  $HN(T_1,T_2) = \text{max acyclic agreement forest - } I \text{Baroni et al.}051$ 

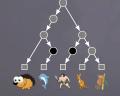
# Networks Display Trees Observation A network may display up to 2|R| trees.

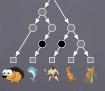
# Networks Display Trees Observation A network may display up to 2|R| trees.

#### Observation

A network may display up to  $2^{|\mathcal{R}|}$  trees. But: how to decide if a given tree is displayed?











Tree Containment Input: a network N, a tree T

Question: Does N display T?

Tree Containment Input: a network N, a tree T

Question: Does N display T?

~> NP-hard (from Disjoint Paths) [kanj et al. '08]

Tree Containment Input: a network N, a tree T

Question: Does N display T?

~ NP-hard (from Disjoint Paths) (Kanj et al: 08]

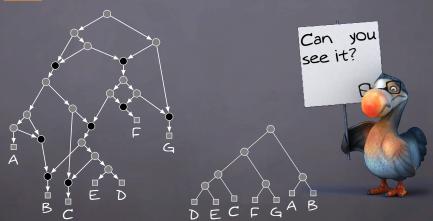
Note: linear time on reticulation visible N (Gunawan; 18] (Weller; 18]

Tree Containment Input: a network N, a tree T

Question: Does N display T?

→ NP-hard (from Disjoint Paths) [kanj et al: 08]

Note: linear time on reticulation visible N [Gunawan, 18][Weller, 18]



# Small Taxonomy of Network Classes

